

Counterexample-guided Cartesian Abstraction Refinement

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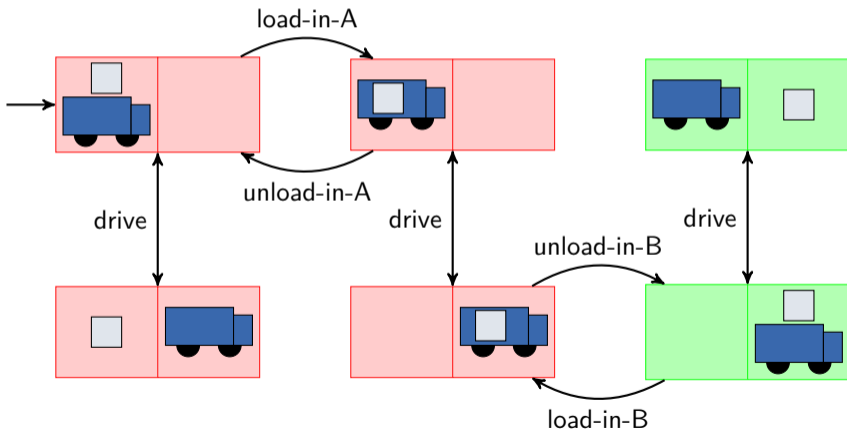
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Overview

- 1 CEGAR algorithm
- 2 Evaluation
- 3 Ongoing research

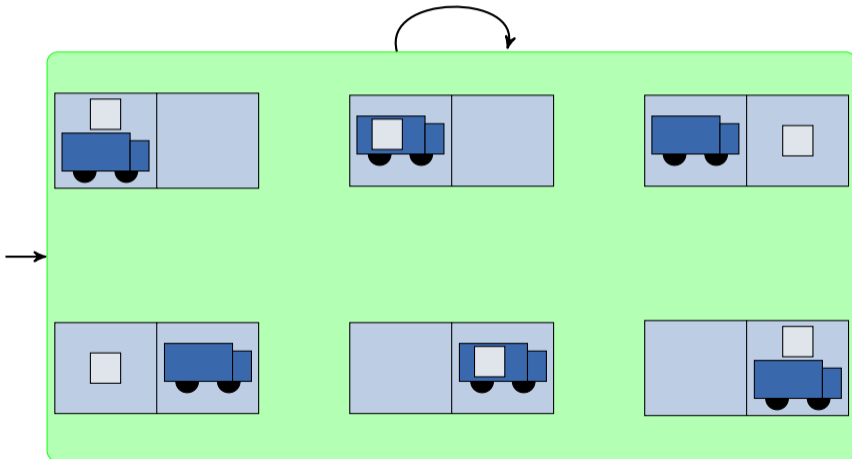
CEGAR algorithm

Classical planning

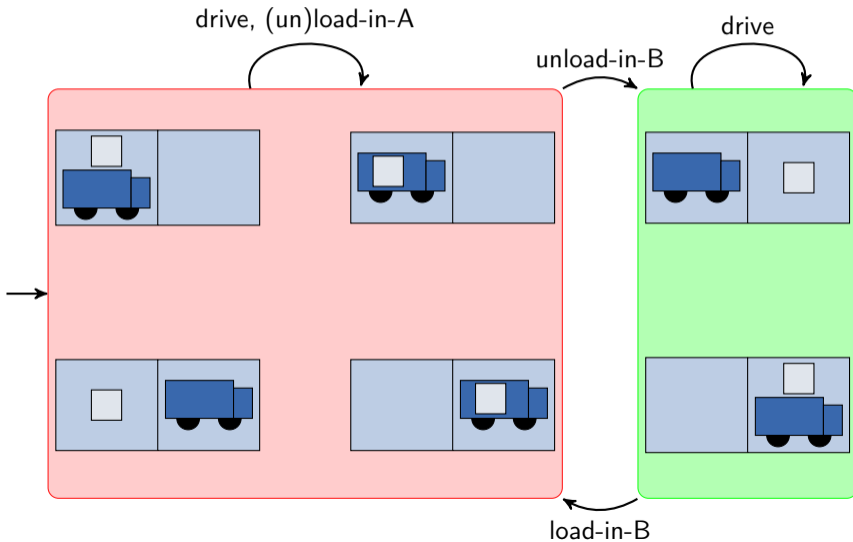


Example refinement

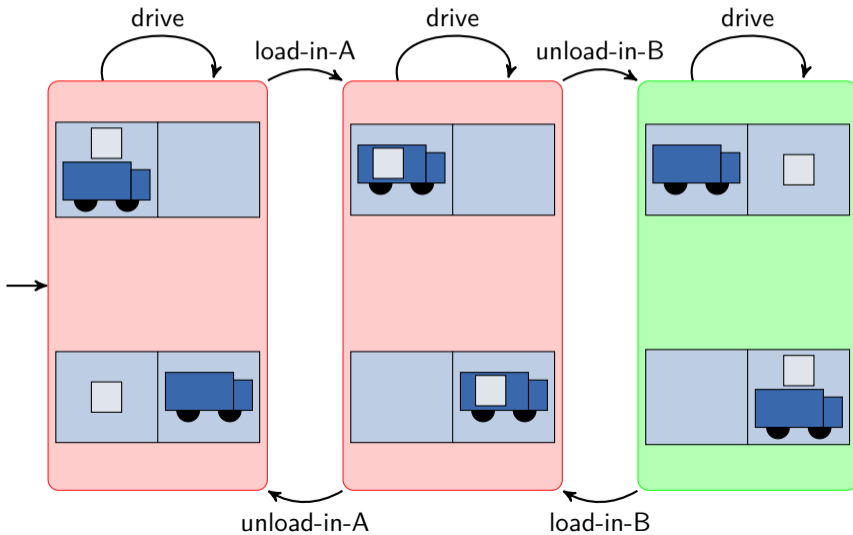
drive, (un)load-in-A, (un)load-in-B



Example refinement



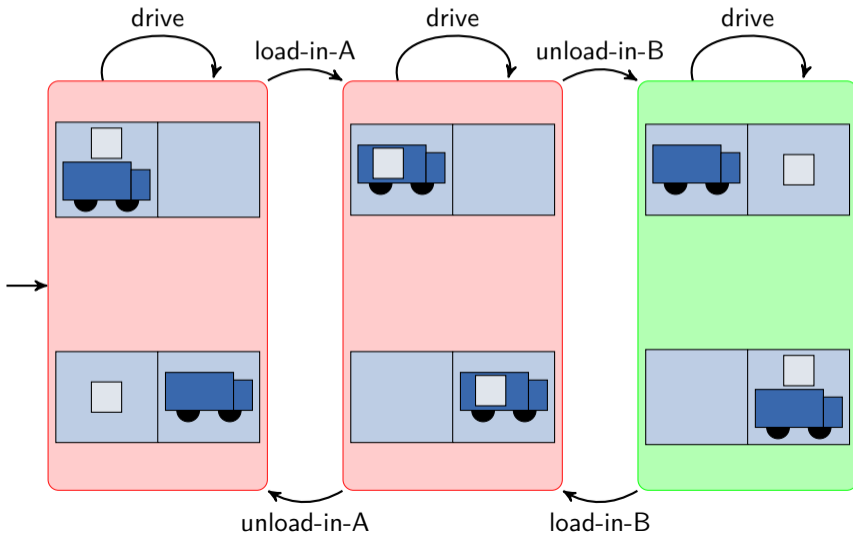
Example refinement



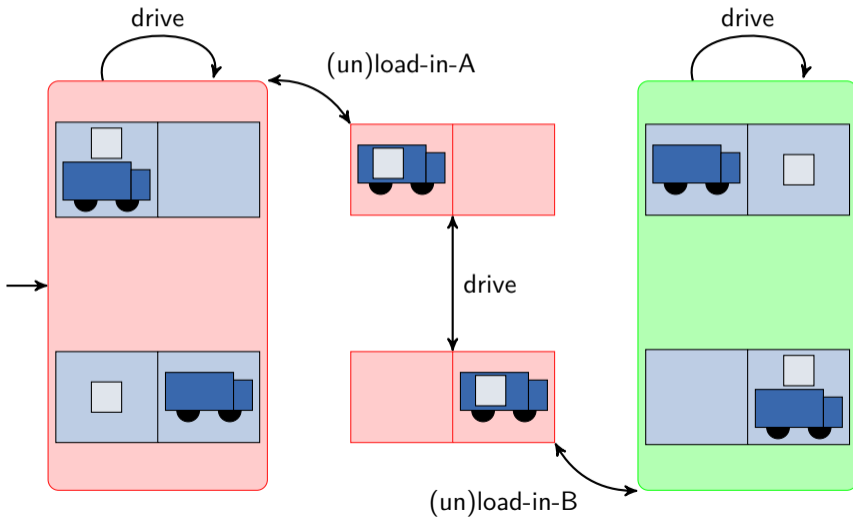
Background

- Relation to other classes of abstractions?

Pattern database



Cartesian Abstraction



Classes of abstractions

- **Pattern databases**
Refinement at least doubles number of states
- **Cartesian abstractions**
Allow fine-grained refinement
- **Merge-and-shrink abstractions**
Preimage of abstract states not efficiently computable

Evaluation

Experiments

Setup

- 30 minutes, 2 GB
- 15 minutes refinement

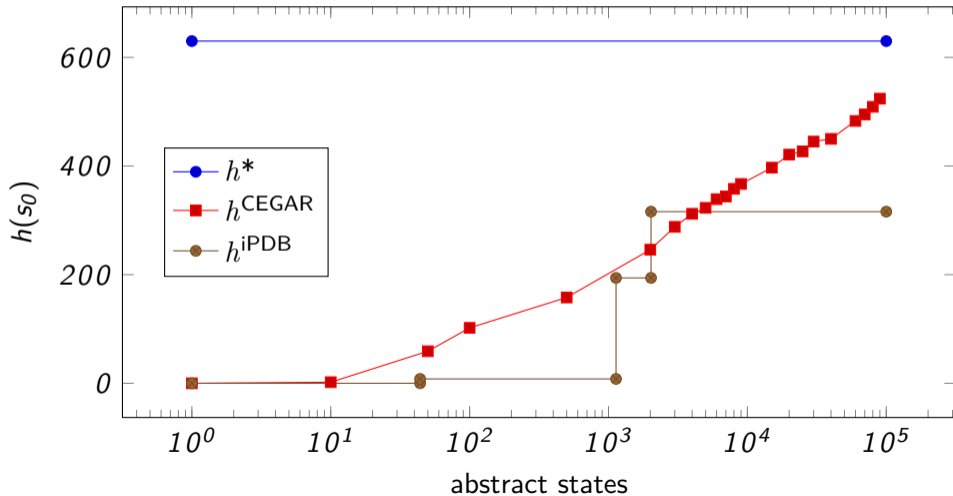
Experiments

Results

| Coverage | h^0 | h^{iPDB} | $h_1^{m\&s}$ | $h_2^{m\&s}$ | h^{CEGAR} |
|-------------------|-------|------------|--------------|--------------|-------------|
| elevators-08 (30) | 11 | 20 | 1 | 12 | 16 |
| miconic (150) | 50 | 45 | 50 | 74 | 55 |
| mprime (35) | 19 | 22 | 23 | 11 | 27 |
| mystery (30) | 18 | 22 | 19 | 12 | 24 |
| ... | ... | ... | ... | ... | ... |
| Sum (1116) | 397 | 450 | 391 | 449 | 441 |
| Worse than h^0 | 0 | 30 | 68 | 40 | 1 |

Experiments

Results – $h(s_0)$ on transport #23



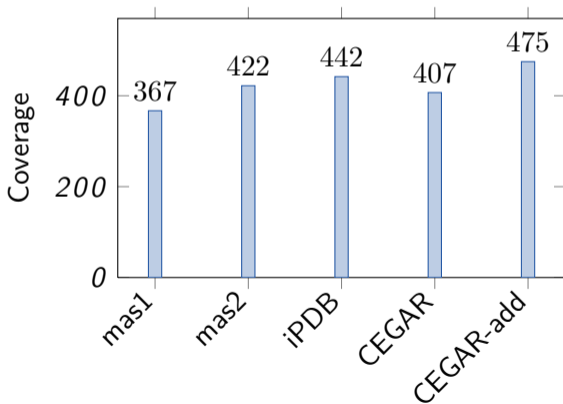
Ongoing research

Current work

- Break all optimal solutions
- Additive abstractions (AAAI-LBP 2013)

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Future work

- How to select flaws?
- Better termination criterion for refinement loop

Conclusion

- CEGAR for classical planning
- New admissible heuristic
- Robust performance

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